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# LUKA GNSS RECEIVER

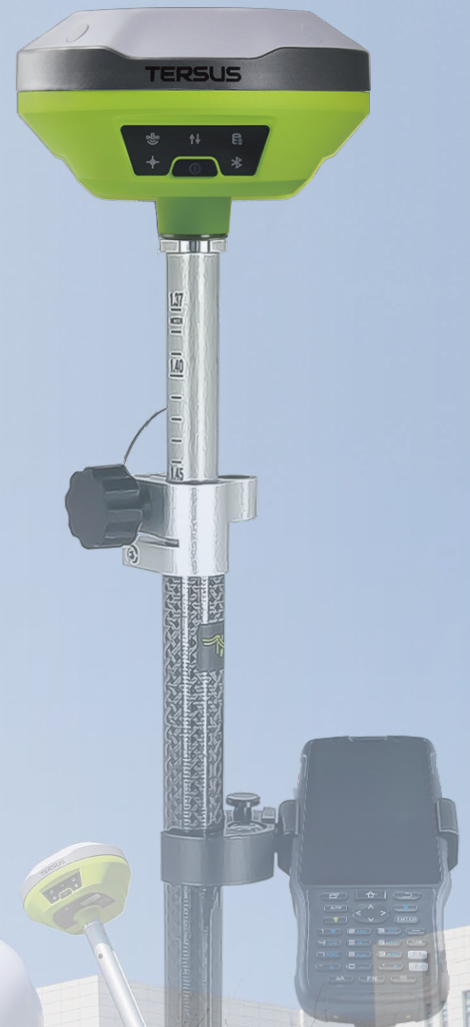
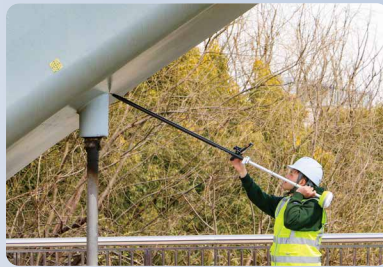
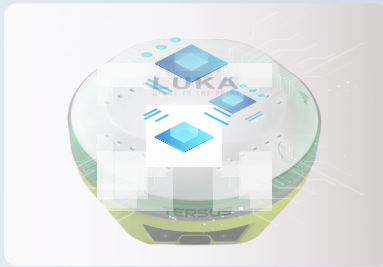
LIGHTER, SMALLER AND SMARTER

➤ SOLUTION READY

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# LUKA GNSS RECEIVER

Smaller, lighter, and smarter. The LUKA GNSS receiver Ultimate version is equipped with a high-precision inertial measurement unit (IMU), which enables tilt measurement immune to magnetic disturbances. With calibration-free tilt compensation, the LUKA GNSS receiver offers reliable flexibility and efficiency, and surveyors no longer to keep the leveling pole upright. Additionally, the LUKA GNSS receiver comes with an internal high-performance multi-constellation, multi-frequency GNSS board that provides highly accurate and stable signal detection.



## Application Scenario



Danger Zone



Hidden Point



Underground  
Utilities



Forest



City Canyon

# Features



**Multiple constellations & frequencies:**  
GPS, GLONASS, BeiDou, Galileo, QZSS.



**3 year warranty** period backed by local Aptella servicing performance.



High-accuracy tilt compensation without calibration, up to **2cm within 60°**, immune to magnetic disturbances.



**Smart battery** with extended working hours and power level display.



**12D Field** Tersus LUKA receiver model support.



**Rich data transmission options:**  
UHF radio, 4G network, Wi-Fi, Bluetooth.



**Intuitive WebUI** for managing receiver status and operation.



**Pre-configured AllDayRTK** settings for ease of setup.



# Technical Specifications

## LUKA

### Performance

Signal Tracking:	
GPS L1/L2/L5;	
BeiDou B1/B2/B3/B1C/B2a;	
GLONASS L1/L2;	
Galileo E1/E5a/E5b;	
QZSS L1/L2/L5	
Channels:	1568
Single Point Positioning Accuracy (RMS):	
- Horizontal:	1.5m
- Vertical:	2.5m
DGPS Positioning Accuracy (RMS):	
- Horizontal:	0.25m
- Vertical:	0.5m
High-Precision Static (RMS):	
- Horizontal:	2.5mm+0.1ppm
- Vertical:	3.5mm+0.4ppm
Static & Fast Static (RMS):	
- Horizontal:	2.5mm+0.5ppm
- Vertical:	5mm+0.5ppm
Post Processed Kinematic (RMS):	
- Horizontal:	8mm+1ppm
- Vertical:	15mm+1ppm
Real Time Kinematic (RMS):	
- Horizontal:	8mm+1ppm
- Vertical:	15mm+1ppm
Initialization (Typical):	4s <sup>(1)</sup>
Initialization Reliability:	>99.9% <sup>(2)</sup>
Network Real Time Kinematic (RMS):	
- Horizontal:	8mm+0.5ppm
- Vertical:	15mm+0.5ppm
Observation Accuracy (zenith direction):	
- C/A Code:	10cm
- P Code:	10cm
- Carrier Phase:	1mm
Time To First Fix (TTFF):	
- Cold Start:	<30s
- Warm Start:	<5s
Re-acquisition:	<1s

### Performance – continued

Tilt compensation accuracy (No tilt angle limit) :	
	≤2cm(within 60°) <sup>(3)</sup>
Timing Accuracy (RMS):	20ns
Velocity Accuracy (RMS):	0.03m/s

### Software Support

Tersus Nuwa

### System & Data

Operating System:	Linux
Storage:	Built-in 8GB
Differential Data Format:	CMR, RTCM 2.x, RTCM 3.x
Data Output:	RINEX, NMEA-0183, Tersus Binary
Data Update Rate:	20Hz

### Communication

Cellular:	4G LTE/WCDMA/GSM/EDG
Cellular Bands:	LTE FDD B1,B3,B7,B8,B20, B28A LTE TDD B38,B40,B41 WCDMA B1,B8 GSM/EDGE B3,B8
Network Protocols:	Ntrip Client, Ntrip Server, TCP, Tersus Caster Service (TCS)
Wi-Fi:	802.11b/g/n
Bluetooth:	4.1

### Internal Radio<sup>(3)</sup>

RF Transmit Power:	0.5W/1.0W
Frequency Range:	410MHz ~ 470MHz
Operating Mode:	Half-duplex
Channel Spacing:	12.5KHz / 25KHz
Air Baud Rate:	4800 / 9600 / 19200bps
Modulation Type:	GMSK, 4FSK
Radio Protocols:	Transparent, TrimTalk450, TrimMark3, South,Satel

### Wired Communication

USB:	Type-C, OTG
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### User Interface

Button:	Power Button
LED Indicators:	Satellite, Correction data, Static, Solution, Bluetooth
Voice:	Support in Nuwa App
Power Display:	Support

### Electrical

External Power Supply:	Support USB (5~20V)
Fast Charging:	Support, 15W max(5V 3A)
Battery:	Built-in, 7000mAh/7.4V
Charing Time:	3 hours (20%~90%)
Battery Charging Temperature:	+10°C ~ +45°C
Working Time:	Up to 19 hours <sup>(4)</sup>

### Physical

Dimension:	φ132x68mm
Weight:	≤ 827g <sup>(5)</sup>
Operating Temperature:	-40°C ~ +70°C
Storage Temperature:	-55°C ~ +85°C
Relative Humidity:	100% not condensed
Dust- & Waterproof:	IP68
Pole Drop onto Concrete:	2m
Vibration:	MIL-STD-810G, FIG 514.6C-1

#### Note:

- (1) The initialization time depends on various factors, including the number of satellites, observation time, atmospheric conditions, multi-path, obstructions, satellite geometry, etc.
- (2) The initialization reliability may be affected by atmospheric conditions, signal multipath, and satellite geometry.
- (3) IMU and built-in radio are optional, details refer to performance comparison table.
- (4) The working time of the battery is related to the working environment, working temperature and battery life. Up to 19 hours working in 4G/3G/2G network and Rover radio mode.
- (5) The actual size/weight may vary depending on the manufacturing process and measurement method.