758-UK

Loadex 100 / LX-100

360 Excavator On-board Weighing System Operation



Electromagnetic Compatibility (EMC)

CE

This product complies with European Council Directive 2014/30/EU when installed and used in accordance with the relevant instructions.

Preface

This manual provides information about operating the "LX-100" system. Correct use and maintenance is important for safe and reliable operation. Please take time to read this manual and complete appropriate training before use before using the system.

Information in this manual is correct at the time of publication. The system may vary slightly from that described herein. Topcon reserves the right to redesign and change the system as necessary without notification.

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Warning

Please read the following important information very carefully.

TERMS AND DEFINITIONS:

Console – The Topcon console mounted inside the cab and used for primary control of the Machine.

Application – An applicable Topcon mobile application product that allows features of Topcon Console(s) to be monitored and controlled from a Device.

Device - A mobile device (e.g. phones and tablets) on which the Application is installed and operated.

System – The combination of the Device and the Console used to control and monitor the Machine.

Machine - The combination of the vehicle and associated attachments.

You – The person using the Application to control and monitor the Machine.

Documentation – The user documentation and manuals relating the use and operation of the covered Topcon product, including, but not limited to, the Console user manuals/materials and Application end user license agreement (as applicable).

IMPORTANT: You must read and follow the Documentation and complete appropriate training before use. If You do not operate the System properly, it can result in damage to property and/or malfunction of the product, death or serious injury to persons. If You are in any doubt regarding any aspect of operating the System, then before commencing operation You should obtain further guidance from a suitably qualified source.

WARNING: It is YOUR responsibility to read and understand the safety sections in this book before operating the system. Remember that YOU are the key to safety.

PRODUCTS/MATERIALS APPLICATION: As limited by the applicable software, You are responsible for accurately entering the information required for the Machine to measure products/materials to Your requirements, including measurement units (e.g. metric or Imperial), weight or other required input. As limited by the applicable software, You are responsible for the calibration of the Machine and ensuring products/materials are measured in accordance with their specifications (e.g. material properties including density).

Without prejudice to the generality of the above You hereby acknowledge and agree that failure by You to comply with the above may result in incorrect operation of the System, or injury to You or others. You should monitor at all times that the System is performing as required.

General Safety



DANGER! It is essential that the following information and the product-specific safety information is read and understood.

Most incidents arising during operation, maintenance and repair are caused by a failure to observe basic safety rules or precautions. Always be alert to potential hazards and hazardous situations. Always follow the instructions that accompany a Warning or Caution. The information these provide aims to minimize risk of injury and/or damage to property. In particular, follow instructions presented as Safety Messages.

Safety Messages and Warnings

The safety symbol is used with the relevant word : DANGER, WARNING or CAUTION. Messages marked in this way recommend safety precautions and practices. LEARN and apply them.



DANGER : Indicates an imminently hazardous situation that, if not avoided, could result in DEATH OR VERY SERIOUS INJURY.



WARNING : Indicates a potentially hazardous situation that, if not avoided, could result in DEATH OR SERIOUS INJURY.

CAUTION : Indicates a potentially hazardous situation that, if not avoided, could result in MINOR INJURY.

Operator Safety

Good safety practices not only protect you, but also the people around you. Study this manual as part of your safety program. This safety information only relates to Topcon equipment and does not replace other usual safe work practices.



WARNING: Never operate the machine with any panels or safety guards removed. Any illustrations or photos in this manual that show panels or guards removed are solely for demonstration purposes. If the removal of panels and guards is necessary for calibration or maintenance, they MUST be replaced before operation.

- Always check that any suspended vehicle attachments or load arm(s) are lowered to the ground before beginning repair or maintenance work on the machine.
- Machine parts can become hot during operation and may be under pressure. Refer to the machine manual(s).
- Wear appropriate protective clothing for the task being undertaken.
- Check the Machine is correctly setup/configured and ready for the intended use.
- Be aware of safety instructions for/on the Machine including hazards such as crush zones.
- Prevent the Machine from being accidentally started if working on it e.g. remove the ignition key, place a warning notice in the cab etc.
- Check that the area of Machine operation is clear of people, animals, and obstacles and identify any other possible hazards.
- Keep other persons required to be in the vicinity of the Machine fully aware of Your immediate intentions.

If an applicable Topcon mobile application is used to augment Your ability to perform tasks that are traditionally performed on the Console directly, then in addition to observing the above warnings and all other pre-determined site safety requirements that apply when operating a Machine from the Console, You must also observe the following additional requirements when operating the Machine via the Application:

- WARNING: The Application must only be operated by You, the single Console operator wholly responsible for the operation of the Machine.
- The Application must only be used when the Machine is not on public roads.
- The Device must be affixed to a rigid mount when used inside the cab while the Machine is moving to avoid a temporary loss of control if the Device is dropped or misplaced.
- The Application must only be used outside of the Machine cab when the Machine is stationary.
- When operating the Application outside of the cab of the Machine You must remain within a reasonable distance such that You can return to the cab-mounted Console in a timely manner to resume control of the Machine under any of the following circumstances:
 - Battery failure on the Device
 - Wifi signal is lost or signal strength is too weak for proper operation
 - The Device is redirected to another application (e.g. a phone call is received)
 - The Device becomes incapacitated (e.g. device is dropped and damaged)
 - Any other event that causes the Device to no longer be fit for control of the Application and/or Machine.
- Stand well clear of any moving parts of the Machine and areas of operation.
- The Device and Machine must be locked when not in use.
- The Device and Machine must never be left unattended.

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1 Overview

The Loadex 100 / LX-100 is a CAN-based system that measures, displays and records the net weight lifted, based on sensing the lift system hydraulic pressure.

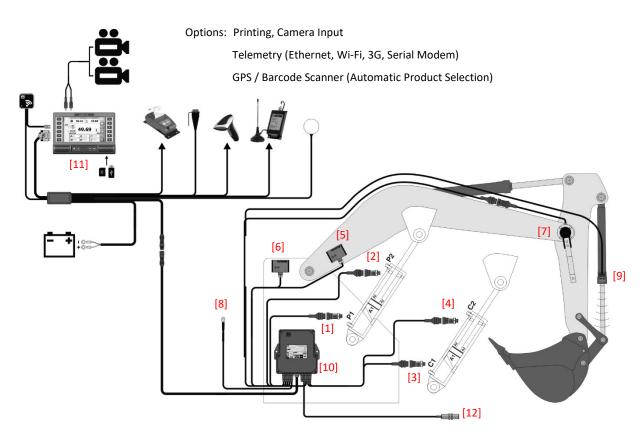
Note: There are differences in the installation of older systems and newer systems, mainly the Weighing Module ECU. Newer systems (WM-X1) also have different harnessing for easier installation, but otherwise both systems employ the same sensors and method of operation.

1.1 Main components

1.1.1 System Overview (older systems)

Two pressure sensors **[1]**, **[2]** are installed into the hydraulic lift system, with possibly two more **[3]**, **[4]** installed on machines fitted with accumulator-assistor cylinders. The pressure signals are captured, filtered and corrected by measuring the angle of the main boom using an inclinometer **[5]**. Slope corrections are made from another inclinometer **[6]** on the chassis. Dipper arm position is made from a mechanical angle sensor **[7]** mounted on the boom to dipper arm pivot.

Figure 1



As an added option, oil temperature compensation is provided by a clamp-on sensor [8]. A bucket position sensor [9] is used to provide reliable and precise bucket compensation.

Note: A secondary Boom Sensor [12] can be installed for machines with an articulated boom.

All signals are processed in a separate Weighing Module **[10]**, and the resultant weight calculation is sent via CANBus to the head unit **[11]**. Load and store information is saved in the head unit where it can be distributed to an in-cab printer, modem or internal SD card.

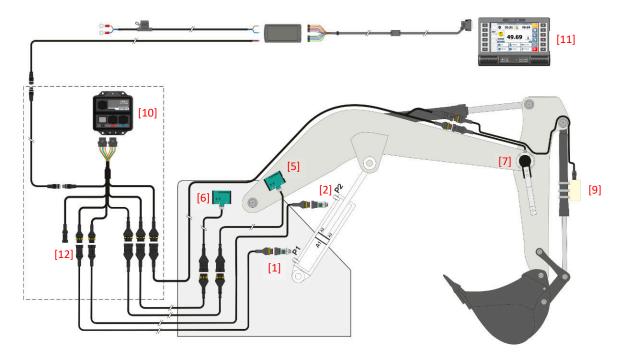
SQL database capability with up to 8 reference fields, provides virtually unlimited inputs of products, customers, trucks, hauliers, locations, destinations, mix blends and notes.

Video input for switching the head unit into reversing camera mode, removes the need for an additional display monitor.

1.1.2 System Overview ('WM-X1')

The latest system with the same functionality, but also designed for easy installation.

Note: It does not have the option of a temperature sensor.



Weighing modes 1.2

When used dynamically, the pressures are captured through a set weighing zone.

The system may also be used in static weighing mode. The boom can either be lifted to a set weighing position where the pressure is captured, or measured constantly in a "live" mode at any required boom height.

Both dynamic and static weighing positions are adjustable by the operator to suit any job required, which will enable the machine to be used at its most efficient output.

Also, weighing while slewing is possible.

Features and Benefits 1.3

GPS Product Recognition

Reversing Camera Input

Adjustable Weighing Height **Oil Temperature and Angle**

Target Load .

Set individual Product target weight to ensure correct loading of vehicles.

- Automatic product selection.
- Single display with automatic switching in reverse gear.
 - Flexible operation according to specific applications.

Accurate weigh information within normal operating temperatures, and on sloping or uneven terrain.

Accurate record keeping, traceability and stock management.

- Calibration for up to 10 Attachments Easy setup when switching attachments e.g. buckets, forks etc. At the pile or above the truck.
- Live Last Bucket 'Tip-off' at any position
- SQL Database

Compensation

- Stores, multiple job and Blend capability with advanced job memory search and Job Report generation
- 5 quick, job pre-selections for repeat job setup

Ease of use and interfacing with ERP systems.

Multiple active job capability.

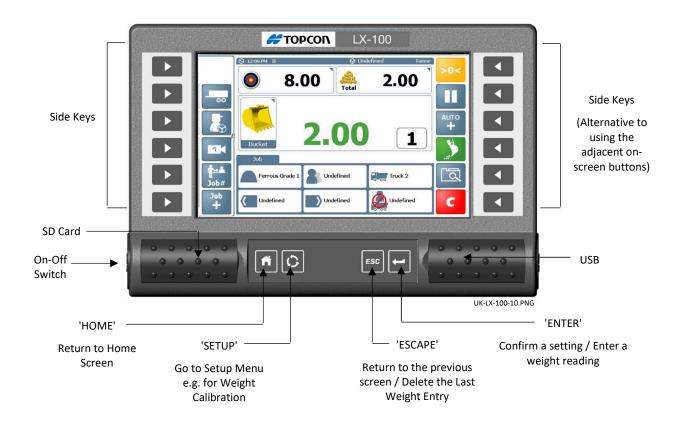
I	GPRS and Wi-Fi connectivity	1-way or 2-way communication with office.
I	 Static and Dynamic weighing modes for 'weighing on the lift' 	Faster operation.
I	 Split loading (Trailers) 	Truck and up to 2 trailers.
I	 Multi-channel and Grand Total summary 	Load accumulation for up to 10 attachments e.g. buckets, forks etc.
I	 XML data output via RS232, Ethernet and USB memory stick 	Safe and efficient data handling.
	 Printing with configurable output 	Hard copy of load summaries and job totals.
I	Calibration 'Nudge'	Quick and easy calibration adjustment to match site reference e.g. weighbridge.
I	Internal Audible Alarm	Set to alarm at overload threshold (90% and 100% of max. load)
I	System 'Pause' mode	Disable weighing mode during non-weighing tasks.

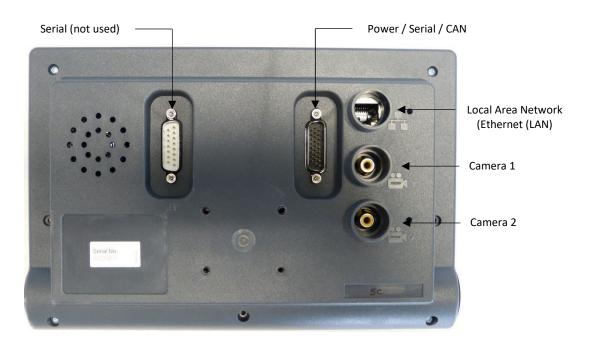
1.4 'Sitelink' Integration

Topcon 'Sitelink' is a cloud-based database application primarily for tracking material moved on a work site, providing operation managers with real time data from machines working on site.

This manual references the standard LX-100 system without Sitelink integration. The user interface for Information Stores will appear slightly different for Sitelink-enabled systems. If your system is enabled for Sitelink connectivity, then please refer to the on-line Sitelink User Guide – section entitled "RDS Weighing Interface", for further information on configuration and Sitelink-specific features on the display unit.

1.5 Features and Controls





1.5.1 Power On

The power switch on the Head unit switches the head unit on and off.

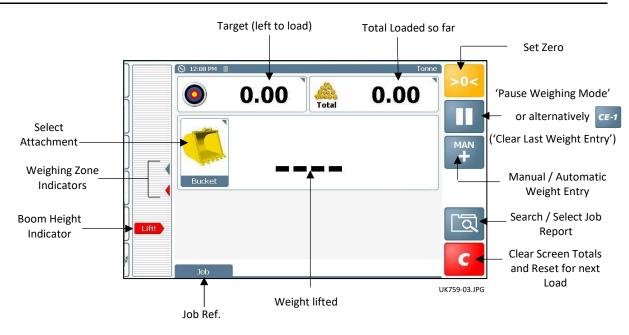
Both the Head Unit and the Weighing Module may be powered either from a permanent +V supply, or a switched +V supply (e.g via the ignition circuit). If powered permanently, the system will automatically go into a 'Standby' mode after 15 minutes of non-use, to save power consumption. If however, the power supply is interrupted (e.g. via the ignition switch or from the battery), the system will take approximately 30 seconds to reboot into the normal operating mode.

NOTE: The system will not boot into the weighing mode unless the SD card containing the LX-100 Database is in place.

1.6 The Home Screen

The functions displayed on the Home Screen depends on which are enabled via the 'Home Screen Functions Setup' menu.

1.6.1 Basic functions only



1.6.2 All functions enabled



Up to 8 Information tabs / Stores displayed from a choice of 12 : e.g. Product, Customer, Truck, Haulier, Location, Destination, Notes, Mix (Mixture of more than one product), Job Name and also Chassis Angle (see below).

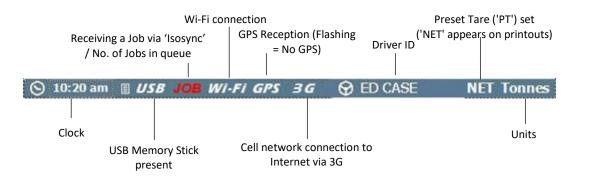
NOTE: There are 3 display options for the left side buttons as configured in the Setup menu, (i) as shown above (temporarily displayed when the boom height indicator area is touched), (ii) as shown above (permanently displayed), or (iii) Job Presets 1-5 (permanently displayed).

1.6.3 Chassis Angle Display



The instrument can be configured via the 'Home Screen Functions Setup' screen in the 'SETUP' menu, to display the Chassis angle (Uphill / Downhill) in place of an Information Store.

1.6.4 The Status Bar



1.6.5 Touchscreen

The instrument has a 5-wire resistive touch screen. 5-wire technology offers superior life and reliability without requiring re-calibration. However, it consists of a polyester film outer layer that must be treated with respect, compared to a non-touch display with toughened instrument glass. Therefore, please observe the following,



- DO NOT use a sharp-pointed object the screen will be damaged beyond repair!
- Do NOT wipe or otherwise attempt to clean using any kind of solvent cleaner!.
- Do NOT wipe using a dirty cloth or gloves. Use only computer screen wipes designed for the purpose!.
- You may use a blunt, smooth-ended plastic object (e.g. a pen body / cap) as a stylus, if found necessary!

1.6.6 USB

The USB socket is intended solely for data transfer, e.g via,

- USB Stick
- USB cable to PC
- External USB Keyboard

Do NOT connect a mobile device to the Isocan for charging purposes. It is not designed to supply a charging current. If you attempt to charge a mobile phone or other device, the current draw may be excessive and the instrument can be damaged as a result.

NOTE: Such damage found to be caused by battery charging via USB will not be repaired under warranty.

2. Operator Settings

2.1 Checklist

Depending on the instrument setup and the type of job, some or all of the following steps may be necessary before you start a weighing job.

- Select Attachment
- Set Zero
- Set Target Load
- Select Automatic / Manual entry Mode
- Select Load References (Reference Stores), or a Pre-defined Job.
- Driver No. etc

2.2 Attachments

Each attachment is configured for the weighing mode, e.g. 'Dynamic', 'Static ON', 'Static OFF', 'Constantly Live Static' or "Slew Auto Trigger". On selection, the instrument is automatically updated to the weight calibration settings and weighing mode for that attachment.

	Select Attachment	
	Swinging Grab	•
Bucket	Swinging Grapple Swinging Bucket	
	X	ESC
		0K

'OK' - Attachment has been calibrated

'X' - Attachment has not been calibrated

Weighing Modes

'OFF'	The attachment is disabled and will not be listed on the 'Select Attachment' screen.
'Dynamic'	Dynamic weighing - Lift through weighing position.
'Live Static Off'	Static Weighing - 'Auto-kickout' operates at the preset weighing position (if connected). At the preset weighing position, the weight is displayed after the 'Static Delay' and 'Static Sample Time' periods NOTE: The weight display remains fixed while at the weighing position.
'Live Static On'	Static Weighing - 'Auto-kickout' operates at the preset weighing position (if connected). At the preset weighing position, the weight is displayed after the 'Static Delay' and 'Static Sample Time' periods NOTE: The weight display is "live" and may change as the 'Static Auto Lock' factor automatically compensates for the effect of pressure loss over time, while at the weighing position.
'Constantly Live Static'	Static Weighing - There is no preset weighing position. A 'live' weight is displayed at any boom position. NOTE: This mode may not be as accurate as 'Live Static OFF' or 'Live Static ON' weighing modes
'Slew Auto Trigger'	The weight is sampled and displayed while slewing. The settings in the "Sensor and Sampling Setup" menu determine the trigger point (i.e. slew speed, duration and direction of slew) in this mode. NOTE: This mode may not be as accurate as 'Live Static OFF' or 'Live Static ON' weighing modes.

2.3 Set Zero



The zero weight reading may drift during regular use. To help ensure accurate weight readings, the zero routine should be done on a regular basis.

Press >0< and follow the on-screen instructions.

NOTE: If the optional 'CHECK ZERO' function has been enabled (it is disabled by default), then the zero routine becomes automated as follows,

'ZERO SYSTEM >0.00<' displays if the system has been switched off, or has not recognised any lifts for more than a preset time period. The 'ZERO SYSTEM >0.00<' routine must be repeated at the end of each preset time period.



The system will countdown 60 seconds before '**ZERO SYSTEM** >0.00<' must be repeated. Weighing is then inhibited until you press $|_{>0<}$ and follow the on-screen instructions.

NOTE: The preset time-period is set from the 'Sensor Setup and Calibration' screen in the SETUP menu. The default time-period is 15 minutes.

The bucket must be lifted and lowered one or more times before commencing the '**ZERO SYSTEM >0.00**<' routine. This ensures the oil is at working temperature. The number of lifts required is also set from the 'Sensor Setup and Calibration' screen in the SETUP menu.

2.4 Target Weight (Weight left to load)



Press and enter the weight required in the truck / trailer.

As you commence the loading cycle, the figure will decrease to show how much is left to load.

2.5 Automatic or Manual Weight Entry Mode

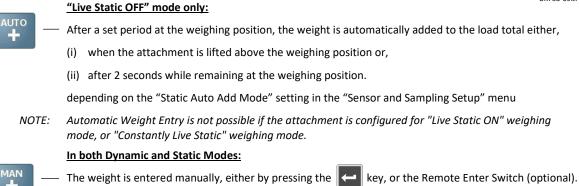


In Dynamic Mode only:

 The weight is entered automatically after the bucket is lifted through the weighing position.



UK758-09.JPG



Slew Auto Trigger Mode

Depending on the settings in the setup menu 'Sensor and Sampling Setup' > 'Slew Auto Trigger', the current bucket weight will be entered automatically either when digging in for the next bucketful, or when dumping the current bucket load.

2.6 Driver ID / Login

The instrument may be programmed with driver names. The current driver is selected from the list and a password entered to confirm.

The driver ID is included in the load data for each completed loading job.

A Job Report can be generated for a specific driver, using the 'Job Search' function (

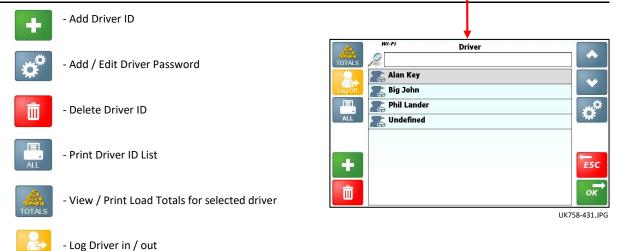
Normally when the instrument is powered on, the driver ID will default to '**Undefined**'. The instrument can however, be setup so the driver must be selected and their password entered on power up, before the instrument will display the Home screen.



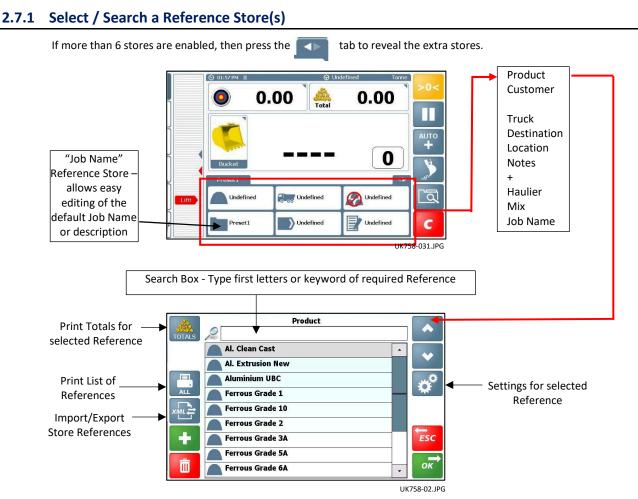
NOTE: The driver ID is displayed in the status bar. If the current job was selected from the job list, and that job was created by another driver, or uploaded prior to you logging on, then their name will be displayed in the status bar. The system can also be configured from the Setup menu ("Limit Jobs by driver"), so that only the jobs allocated to the logged-in driver are visible in the Job list.

You can edit the driver ID for a job to your own ID, via the Jobs List (ref. section 2.8).

2.6.1 Edit / Print / Delete Driver ID / Password



2.7 Reference Stores



The screen layout is similar for other Reference Stores except for 'Haulier' and 'Mix'.

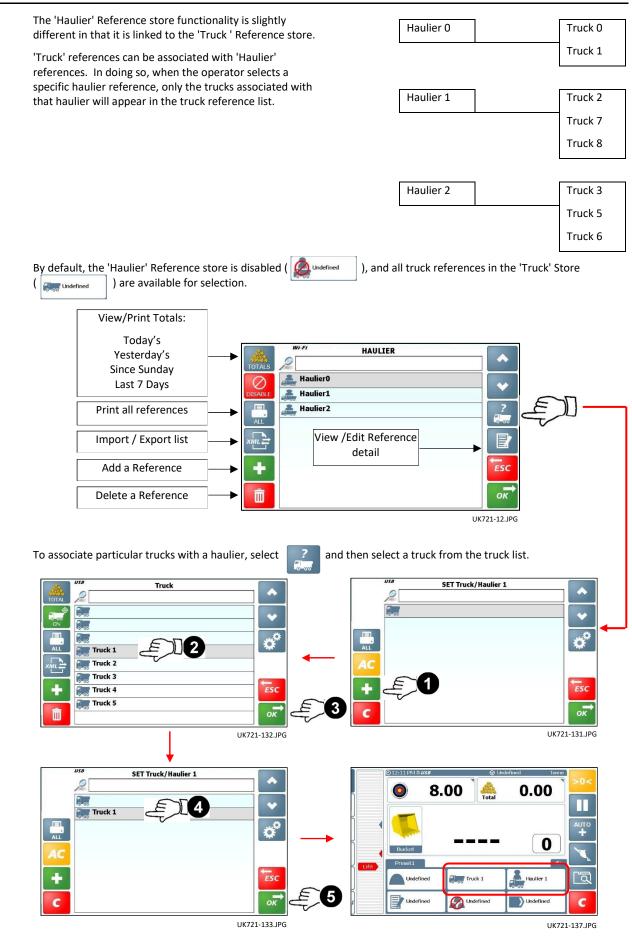
2.7.2 Import / Export Reference Stores

Store References (and the load data linked with them), are stored in the database on the SD card. The data can be updated by importing .XML data edited in PC software, or likewise exported in .XML format for administration purposes.

Press for the Import / Export options available. Each Reference Store has these options. You are prompted to enter a suitable filename.

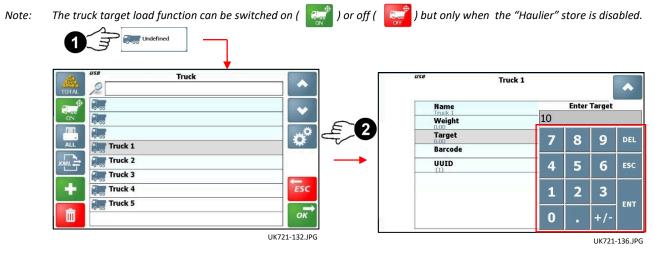
IMPORT / EXPORT	
EXPORT LIST VIA EMAIL	
EXPORT LIST TO WEB SERVER	
IMPORT LIST FROM WEB SERVER	
EXPORT LIST VIA USB	
EXPORT LIST VIA ANDROID DEVICE	
IMPORT AND OVERWRITE LIST VIA USB	_
IMPORT AND ADD TO LIST VIA USB	ESC
	ок
	UK721-24.IF

NOTE: Not all the options may appear as shown, depending on your setup.



2.7.4 Set Truck Target Weight

A pre-programmed target quantity (either by weight or number of bucketfuls) can be pre-programmed for each truck. When the truck reference is selected, the target load is automatically set on the main weighing screen.



2.7.5 Enable the Blend ("Mix") Reference Store

You can create and store any no. of 'Blends'. A blend is a combination of different products and their proportions that make up a 'mix'.

By default, the 'Mix' Reference store is disabled.

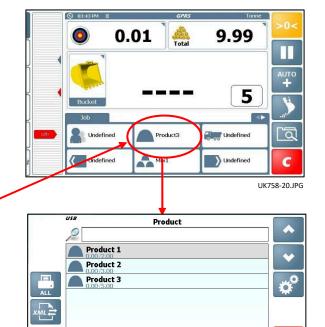
Press on. to switch Blend ("Mix") mode

When Blend ("Mix") mode is on, the normal Product Reference list is not available.



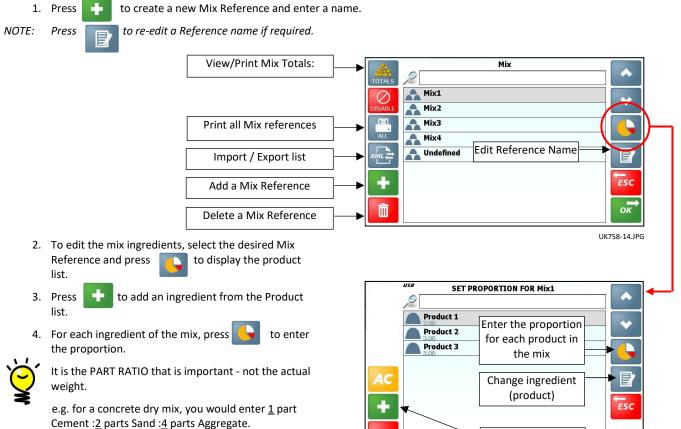
Touching the Product icon on the 'Home' screen, lists the individual ingredients of the Mix and their calculated weights, based on the target weight entered.

It is possible to exit the Blend ("Mix") mode (e.g. to perform an interim loading task) at any stage of blending, and then return to the blending task later (ref. 2.8 - Jobs List).



ESC

ОК



The instrument automatically calculates the actual weight of each ingredient, according to the target weight you enter on the Home screen.

Add ingredient

(product)

UK721-300.JPG

2.7.6 Create / Edit a Blend ("Mix") Reference

2.8 'Jobs' List

- Jobs to do / Active jobs list ("Job #"): - A list of jobs to be done, or jobs in progress.

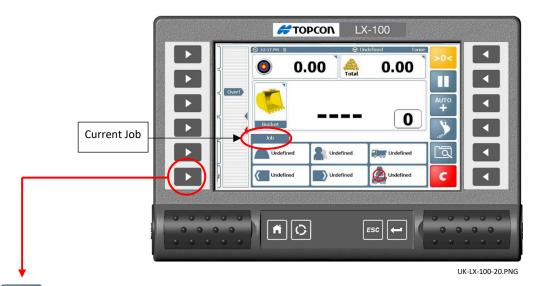
In addition to 5 permanent 'presets', jobs can be uploaded in .XML format via USB memory stick, Telemetry (via Isosync), or can be manually input by the operator.

NOTE: When a job or jobs are received via telemetry, the "JOB" logo appears on the status bar, and alternates with a number indicating the no. of jobs that have been transmitted.

Each job in the job list shows the following information,

- Job Name.
- Target Load / Total Loaded so far.
- Store Reference Names for Stores 1, 2 and 3.

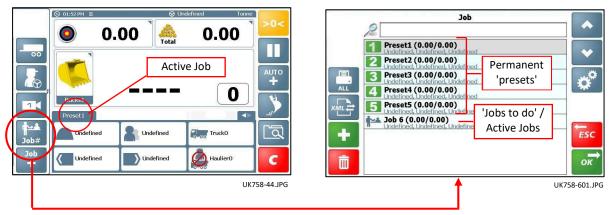
2.8.1 Manually selecting a Job from the Jobs List



The operator can select the jobs in any order.

Once selected, a job does not have to be completed and cleared before starting another job. This enables the operator to perform and log multiple loading tasks e.g. in a busy environment.

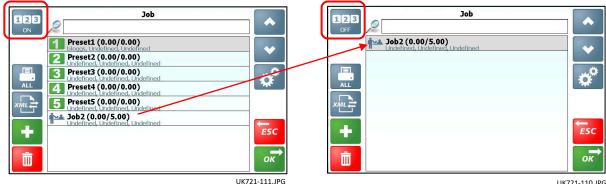
For example, by selecting to access the job list, the operator could switch from loading a truck to adding more material to a crusher, and likewise switch back again to finish loading the truck.



2.8.2 Selecting a 'Preset' Job

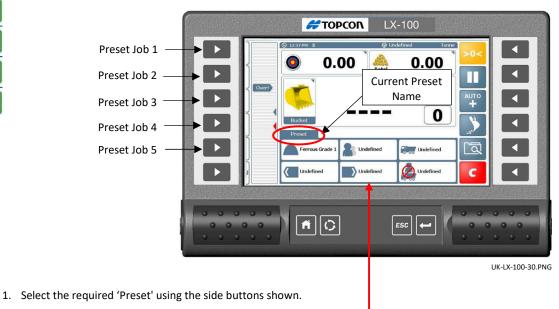
If you have particular jobs that are done repeatedly with the same Store references, like the preset channels on a radio, you can quickly select a preset 'job' from the list without having to keep manually selecting the Store references.

NOTE: The 'Preset' functions can be disabled from the Jobs List screen. For example, if all jobs are to be created and then transmitted via telemetry to the instrument.



UK721-110.JPG

- Permanent 'presets': ("Preset Job #"): - These 5 presets will always appear at the top of the 'jobs' list.



- 2. The Store References may be edited if required.
- 3. Set the Target Weight and start to load (ref. section 3).
- NOTE: When a preset job is cleared, the Store References will return to the programmed preset reference names. If the names need to be modified, then edit the required names and then press and hold the relevant preset button for 5 seconds. A long beep will sound, confirming the new reference name has been stored.

2.8.3 Starting another Job before the current Job is cleared

4. To start another job (preset or non-preset) before the current job is completed and cleared, either press another preset, select another job from the job list (2.8.1) or add a new job (2.8.5), and continue as above.

The load data for uncompleted jobs is stored, and can be returned to for completion as required.

2.8.4 Automatic Job creation after the current Job is cleared

- 5. When a job is cleared (preset or non-preset), the system then automatically creates a new job. The new job will either be automatically named "Job", or you are prompted to manually enter a job name ^{[1].}
- [1] Please refer to the setting 'Add Job Name' in the Database Setup' menu.
- 6. The store references automatically set ^[2] for the new job will be either,
- (i) the references of the last job completed.
- (ii) "Undefined" references.
- (iii) the references of the last preset job completed.
- [2] Please refer to the setting 'Clear Options' in the Database Setup' menu.

You can continue to use the automatically-created 'Job' or if required re-select a 'Preset', or another Job from the 'To Do' List.

7. If no lifts were added to the automatically-created 'Job' prior to re-selecting a 'Preset', that job is automatically deleted from the Jobs list. This prevents unwanted automatically-created jobs accumulating in the Jobs List.

2.8.5 Add a New Job

As well as jobs being uploaded to the LX-100 from an external source, the operator can manually input new jobs as required.

NOTE: There are 3 display options when adding a job, configured via the the "Database Setup" page in the Calibration menu,

(i) A new job is created with the default job name "Job".

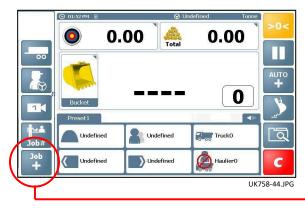
(ii) You are prompted to enter a job name via the on-screen keyboard.

(ii) You are prompted to enter a BIC code via the on-screen keyboard.

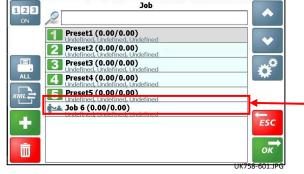
You can subsequently edit the name via the 🧬 button on the Jobs List page, if you wished to change it.

When entering a new job, it will appear as the active job on the main screen, with 'Undefined' for the Store References. The new job will also appear on the Job List page.

You can then set the required Store References either from the main screen (or from the Jobs List).



Job 6 1 2 3 4 5 6 7 8 9 0 • aB . , : ; ? ! • • & @ % 14
. , : ; ? <u>!</u> ⁻ ' & @ % 1/
- * / = < > () \$ € £ ¥ ¢



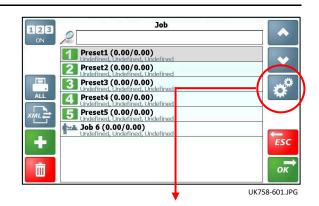
2.8.6 Edit Preset Jobs / 'Jobs to Do'

You can manually edit the Store References, Driver name and Job Name for any 'Preset' / 'Job to Do' in the Jobs list.

- 1. From the '**Jobs**' screen, press to select the Edit screen.
- 2. Select the information line to edit.
- Press to select the required Store information.
 For example,

If selecting 'Customer', the Customer Store list will be displayed, from which you can select the required customer reference.

NOTE: The Store References can also be edited from the "Home" screen (2.8.2), then stored by pressing and holding the relevant Preset key for 5 seconds.



1	Preset1		*
2 3 4 5	Time & Date 13/7/2012 08:58 AM Proset1 Proset1 Chedefined Product Driver Undefined Product Driver Undefined Product Driver Undefined Undefined Undefined Undefined Undefined Undefined Undefined		
Item	Destination Undefined	•	
		UK	758-53.JPG

2.8.7 Switching Jobs and Presets

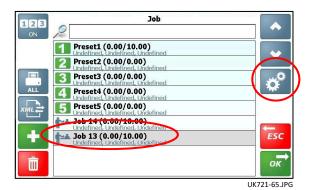
Any job in the job list can be assigned to one of the 5 preset positions. Likewise, the preset jobs can be re-arranged in a different order if desired.

Jobs and Presets can be interchanged via the Jobs List screen page.

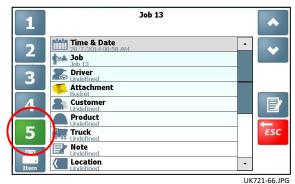
Switching via the Jobs List screen page

For example: Assigning a job (Job 13) to Preset 5.

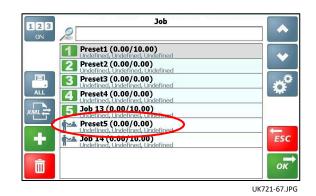
1. Select the job to re-assign and press



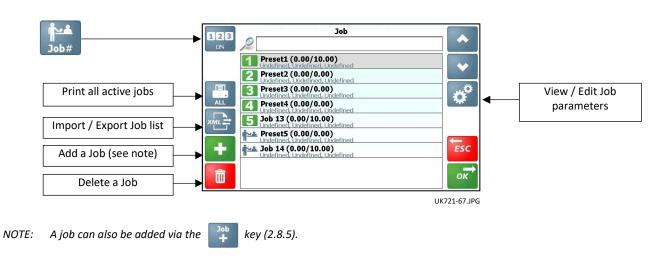
- 2. Select the preset to assign the job to.
- 3. Press ESC to return to the Home screen.



4. The jobs switch places. Job 13 is now Preset 5, and the job that was previously Preset 5 is moved down to the job list.



2.8.8 Add / Delete / Print Jobs



2.8.9 Import/Export Jobs List

The Jobs list is stored in the database on the SD card. The data can also be updated by importing .XML data edited in PC software, or likewise exported in .XML format for administration purposes.

Press XML

in for the Import / Export options available. You are prompted to enter a suitable filename.

IMPORT / EXPORT	
EXPORT LIST VIA EMAIL	
EXPORT LIST TO WEB SERVER	
IMPORT LIST FROM WEB SERVER	
EXPORT LIST VIA USB	
EXPORT LIST VIA ANDROID DEVICE	
IMPORT AND OVERWRITE LIST VIA USB	_
IMPORT AND ADD TO LIST VIA USB	ESC
	ок

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2.9 Set Product Density / Price per Unit

If a volumetric unit (m³ or yd³) is selected, then the DENSITY of the product must be entered on the Product Store Information screen.

Press	Undefined	to select th		ct Reference store. Select the refe	erenc	e to edit th	en press 🕵
			USB	Flint chippings Plint chippings Icon Second Icon Density Barcode GPS Latitude	• •	• • • • • • • • • • • • • • • • • • •	— Edit value

NOTE: If weighing volumetrically, failure to programme the product density will result in incorrect weight measurement and memory totals !

2.10 Adjusting the Weighing Position

The weighing height is initially set as part of the calibration procedure. However, it may be found desirable to re-adjust the weighing position during the loading cycle. There are two options – adjustment via the SETUP screen or via a remote switch.

2.10.1 Weighing Height Adjustment via the SETUP screen

- (i) Press 🗘 to select the SETUP screen, then press
- (i) Follow the screen instructions.
- NOTE: If the attachment is configured for Static weighing mode, then you will instead be prompted to lift the boom to the 'KICKOUT ANGLE'. In other respects however, the procedure is the same.

	4\12	Bu	icket
	DYNAMIC ST	ART POINT	
	Lift Boom to required S	start of Weighing arc	
-10°	·		SKIP
	Press Ok	(to set	ESC
	Dynamic Start Angle	-10°	250
	Horizontal Angle	1°	ок

UK759-11.JPG

2.10.2 Weighing Height Adjustment via a Remote weighing switch

Not to be confused with the optional "Remote Enter switch" (for manual weight entry), a "Remote Weighing switch" is used to set the weighing position "on the go". It is particularly useful in material recycling applications, where a material handler is grabbing material from one or more piles, and therefore the weighing height constantly needs to be changed. By using a Remote weighing switch, the weighing process can be seamlessly integrated into your normal work flow.

Depending on the particular machine, the Remote weighing switch installation may either utilize an existing, redundant button on the righthand joystick, or be a foot-operated switch unit. The system may be configured so that the "Remote weighing switch" either,

- (i) simply sets the weighing position, or
- (ii) sets the weighing position <u>and</u> initiates weighing and automatic weight entry.
- NOTE: Configuration is via "Static Auto Add Mode" in the "Sensor and Sampling Setup" menu.

- (i) Weighing by lifting above the weighing position
- NOTE: "Dynamic" / "Live Static OFF" weighing modes

When the switch is operated, the weighing position is set 5° above the current height of the attachment. As you continue lifting the attachment, depending on the weighing mode set, you will either pass the 'Dynamic Start Point' where weight sampling begins (Dynamic weighing mode), or reach the 'Kickout Angle' where you then pause as the weight is sampled. (Static weighing mode).

If AUTO ENTER (+) is set, the weight is automatically added to the load total when the attachment is lifted above the weighing position.

If MANUAL ENTER (👫) is set, then press the 🗲 key to add to the load total.

(ii) Automatic weight entry after a preset time

NOTE: "Live Static OFF" weighing mode only.

The weighing position is set at the moment that you stop the lift and operate the switch. The weight is sampled and a fixed weight reading is then displayed on-screen.

If AUTO ENTER (400) is set, the weight is automatically added to the load total after 2 seconds.

This mode is intended primarily for material handling situations necessitating a high weighing position. It avoids having to raise the load any higher than during the normal (i.e. non-weighing) transfer process.

3 The Loading Cycle

3.1 Machine Requirements

The accuracy of the system depends to some extent on the following :

- 1. Operating Temperature : Always allow the machine and the hydraulics to warm up to the normal operating temperature before commencing weighing.
- 2. Weighing on level ground : The chassis angle sensor provides automatic correction if weighing on a slope.
- 3. Boom lift and vehicle movement : Anti-bounce compensation and filtering help to maximise weighing accuracy. Best results are obtained when weighing while the vehicle is stationary.
- 4. Maintenance : Keep your machine maintained in good condition. Things like excessively worn bushings, pivot pins etc, as well as lack of lubrication to these areas can have an adverse effect on weighing accuracy. After any major servicing particularly if you have replaced worn components or carried out welding repairs, you should re-calibrate the weighing system. If the hydraulic system has been drained and re-filled, you should also check for any air that may have become trapped at the pressure sensor(s).

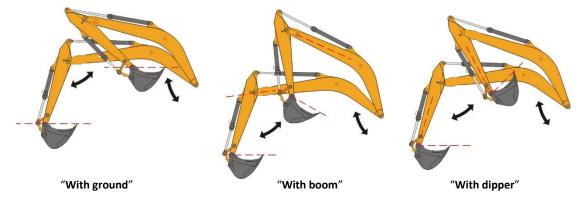
3.2 Lifting Procedure

The correct lifting procedure is especially important for dynamic weighing. The best procedure is as follows,

- 1. Having picked up the load, angle the attachment to the position for weighing. The options are either,
- (i) Keep attachment angle fixed relative with ground (e.g. a bucket or swinging attachment).
- (ii) Keep attachment angle fixed relative with boom (e.g. a bucket attachment).
- (iii) Keep attachment angle fixed relative with dipper (e.g. a fixed grab attachment).

The attachment position is set as part of the bucket calibration procedure when the system was first calibrated. It is important to weigh with the attachment at the correct angle, since it is a very important factor in achieving consistent and accurate weighing.

Attachment weighing position options



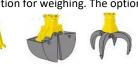
Weighing will be inhibited unless the attachment is at the correct position.

2. Lift smoothly without bouncing or jerking, at the correct lift speed.

In Dynamic Weighing mode, the system has lift speed compensation and will alert the operator in the event the lift speed is too fast or too slow.

In Static Weighing mode, the system has automatic compensation and filtering when the load is stationary at the weighing position.





3.3 Dynamic Weighing Mode

With dynamic weighing, the load is lifted without any interruption. Weighing can be fully automatic and quick.

If GPS Product recognition is enabled (ref. section 4), then the Product reference is automatically set when the machine

- 1. Make sure the machine is at normal operating temperature.
- 2. Select any required load references (product, customer, truck etc).

comes within range of the product location, and reverse gear is selected.



3. Zero the attachment. Follow the routine on the screen.

4. Load the attachment as normal and lift smoothly at a constant speed through the indicated weighing "zone", maintaining the attachment at the correct angle (ref. 3.2).

Once the weighing zone is passed, the lifted weight is displayed.



If the Overload audible alarm is enabled,

At 90% of maximum load = intermittent tone At 100% of maximum load = continuous tone



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5. If AUTO ENTER (400) is set, the weight is automatically added to the load total.

If MANUAL ENTER () is set, then PRESS the key (or the Remote Enter Switch if fitted), to add to the load total.

The target weight ()) will decrease by the calculated weight to show how much is left to load.

The 🮎 figure then indicates the total of all bucket weights entered so far.

 Continue loading until you get to the last bucketful. If the bucket weight exceeds the target required, the bucket weight turns RED.

Regardless if "Auto Entry" (\rightarrow) is enabled, the system does not automatically enter the "last bucket" weight unless configured to do so ^[1]. You have to manually enter the weight using the Remote Enter button (if fitted), or the **r** key.

 Image: Second state of the second s

UK758-061.JPG

^[1] If "Auto Add Over Target" is enabled (via the 'Database Setup' menu), then the "last bucket" load will be automatically entered even if the target load is exceeded.

However, there are several methods for "Last Bucket" weighing (ref. section 3.4)

7. Press C to reset for the next loading job.

A 'Job Record' that includes the Load Data and Store references, is saved automatically to the database on the SD card, and printed out (if setup to do so).

A new Job is then created (ref. section 2.8.4). Depending on the setting in the 'Setup', menu, the Store References will either default to those of the previous job, or to '**Undefined**'.

The "Target Load" will revert to the last figure entered, and will need to be changed only if the next truck requires a different weight.

NOTE: Once started, a job does not have to be completed and cleared before starting another job. This enables the operator to perform and log multiple loading tasks e.g. in a busy environment (ref. 2.8 - 'Jobs List').

3.3.1 "Slew Auto Trigger " Weighing

This mode is a way of dynamic weighing that allows the operator to weigh without having to interrupt the natural movement of the excavator arm during the loading cycle. Irrespective of the height or reach of the dipper arm, weighing is triggered automatically when the slew speed is within the speed range set, and the arm is slewing in the selected direction.

Depending on how your system is configured, "Slew Auto Trigger" mode can be selected (via the attachment icon () for more than one loading attachment (or as a selectable weighing option for a single attachment).



The way in which "Slew Auto Trigger" weighing operates is determined by several programmable settings in "Slew Auto Trigger" mode, (enabled via the 'Sensor and Sampling Setup' > 'Slew Auto Trigger' menu).

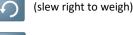
There are two options for the method of operation – 'Manual' and 'Auto' slew direction.

'Manual' Slew Trigger direction

If "Slew Trigger direction" is set to 'Manual', you preselect the direction of slew that will trigger weighing.

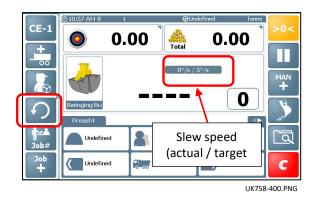
Note:

The slew direction key replaces the reversing camera select key.



(slew left to weigh)

The weight is taken when the preset slew speed is maintained over the preset time period, and is then displayed.



If AUTO ENTER ($\overset{\text{Auro}}{+}$) is set, the weight is automatically added to the load total.

If MANUAL ENTER (👫) is set, then PRESS the 🛹 key (or the Remote Enter Switch if fitted), to add to the load total.

The system then resets for the next weighing cycle.

'Auto' Slew Trigger direction

The slew direction key is not present, as weighing will be triggered when slewing in either direction. The weight is taken when the preset slew speed is maintained over a preset time period and is then displayed.

If AUTO ENTER ($\stackrel{\text{Auro}}{+}$) is set, the weight is automatically added to the load total.

If MANUAL ENTER () is set, then PRESS the key (or the Remote Enter Switch if fitted), to add to the load total.

Further weighing is inhibited until either,

- (i) the bucket load is dumped.
- (ii) The bucket digs in for the next load.

The system then resets for the next weighing cycle.

Note: The mode of operation (i) or (ii), is determined by the % setting in the 'Slew Auto Trigger' menu. Please refer to the calibration manual for further information.

3.4 "Last Bucket" Weighing

When in either Dynamic or Static weighing mode, if the weight exceeds the target required, the weight display turns **RED**. Regardless if "Auto Entry" ([[]]) is enabled, the system does not automatically enter the "last bucket" weight. You have to manually enter the weight using the Remote Enter button (if fitted), or the [] key.

There are several methods for "Last Bucket" weighing.

3.4.1 "Undo last Lift" (Dynamic / Static Weighing Mode)

If the last added lift is too much, the operator may wish to simply cancel the last lift, tip off some material back onto the pile, and weigh again.

- 1. Press the **esc** key, and select "**Undo Last Lift**". This will subtract the last lift from the weighing screen and the Store totals.
- 2. Tip out some material and then lift again through the weighing zone, until the required amount has been weighed and added again to the total.

NOTE: If setup via the 'Home Screen Functions Setup' page in the calibration menu, a 'Clear Last Entry' function (ceri) replaces the 'Pause' function () on the weighing screen.

This then allows you to immediately remove the last lift from the total with a single key touch.

3.4.2 "Reweigh the Remainder" (Dynamic / Static Weighing Mode)

In some cases where the truck also has an on-board weighing system, the operator may tip a partial amount off the "last bucket" load to "top-off" the truckload, as directed by the truck driver.

The "re-weigh" function enables the weight of the material remaining in the bucket to be re-weighed and subtracted from the truck total, ensuring the recorded total matches the actual weight loaded into the truck.

- 1. Press the ESC key, and select "Reweigh the Remainder".
- 2. Lift again through the weighing zone. The weight of material remaining in the bucket is subtracted from the truck total.

3.4.3 Live Static "Tip-off" Mode

"Undo last Lift" and "Reweigh the Remainder" "last bucket" weighing are trial and error methods. To assist in measuring the amount required for the last dynamic weighing, the "Live Static Tip Off" feature may be used.

- 1. Lift up to any suitable height, and then press the button. The "live" calculated weight, and button icon are then shown in **GREEN**. The weight shown is now live.
- 2. Allow the live display to settle down before checking the true weight.

"Live Static Tip Off" can be configured to operate in either of two ways,

- 3(a) Tip off material back onto the pile ("Pile Tip Off Manual Add On" configuration). The instrument displays the weight remaining in the bucket as you tip the surplus material back onto the pile.
- 3(b) Tip off material into the truck ("Truck Tip off" configuration). The instrument displays the weight tipped off the bucket into the truck (to match the 'weight left to load' display).
- 4. To enter the 'Live Tip-off' weight, press the Remote Enter button (if fitted), or the 🛏 key.
- NOTE 1: "Live Static Tip-off Mode" must be configured to "Pile Tip Off (Manual Add On"), otherwise weight entry is not possible whilst remaining in Live static mode. "Live Static Tip-off Mode" is configured from the 'Sensor Sampling and Setup' screen ('Factory' calibration menu).

3.5 Static Weighing Mode



1. Make sure the machine is at normal operating temperature.



If GPS Product recognition is enabled (ref. Section 4), then the Product reference is automatically set when the loader comes within range of the product location, and reverse gear is selected.

- 3. Zero the attachment. Follow the routine on the screen.
 - 4. Load the attachment as normal and lift the load up to the weighing position. The alarm will sound one beep and either the "live" weight or captured weight will be displayed. Keep the machine as steady as possible while the weight is taken.

The instrument will display 😈 indicating that the weight is being sampled, and the bucket weight is then displayed.



If the Overload audible alarm is enabled,

At 90% of maximum load = intermittent tone At 100% of maximum load = continuous tone



- 5. If AUTO ENTER () is set, and depending on the "Static Auto Add Mode" setting in the "Sensor and Sampling Setup" menu, the weight is automatically added to the load total either,
- (i) when the attachment is lifted above the weighing position or,
- (ii) after 2 seconds while remaining at the weighing position.

NOTE: Also reference section 2.10.2.



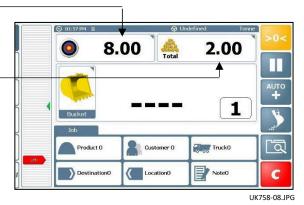
Automatic Weight Entry is not possible if the attachment is configured for "Live Static ON" weighing mode, or "Constantly Live Static" weighing mode.

If MANUAL ENTER (💾) is set, then press the 🗲 key (or the Remote Enter Switch if fitted), to add to the load total.

The target weight () will decrease by the calculated weight to show how much is left to load.

The 🧱 figure then indicates the total of all bucket weights entered so far.

Continue loading until you get to the last bucketful. If the bucket weight exceeds the target required, the bucket weight turns RED. Regardless if "Auto Entry" (^{Auro}/₁) is enabled, the system does not automatically enter the "last bucket" weight unless configure to do so ^[1]. You have to manually enter the weight using the Remote Enter button (if fitted), or the provide the system of the system.



^[1] If "Auto Add Over Target" is enabled (via the 'Database Setup' menu), then the "last bucket" load will be automatically entered even if the target load is exceeded.

However, there are several methods for "Last Bucket" weighing (ref. section 3.4).

7. Press **C** to reset for the next loading job.

A 'Job Record' that includes the Load Data and Store references, is saved automatically to the database on the SD card, and printed out (if setup to do so).

A new Job Is then created (ref. section 2.8.4). Depending on the setting in the 'Setup', menu, the Store References will either default to those of the previous job, or to '**Undefined'**.

The "Target Load" will revert to the last figure entered, and will need to be changed only if the next truck requires a different weight.

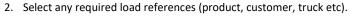
NOTE: Once started, a job does not have to be completed and cleared before starting another job. This enables the operator to perform and log multiple loading tasks e.g. in a busy environment (ref. 2.8 - 'Jobs List').

3.6 Static Weighing - 'Constantly Live Static' Mode

If the weighing mode for a selected attachment is set to 'Constantly Live Static', the live weight is displayed at any boom position.

Weighing in this mode will not be as accurate as with other weighing modes. However, to get the best accuracy possible, it is recommended to always enter the weight reading at the same boom position every time. This position should ideally be the weighing position at which the attachment was calibrated.

1. Make sure the machine is at normal operating temperature



If GPS Product recognition is enabled (ref. Section 4), then the Product reference is automatically set when the loader comes within range of the product location, and reverse gear is selected.

- Lift the load and stop at a convenient boom position, and the "live" weight will be displayed. Keep the machine as steady as possible while the weight is taken.
- NOTE: There are no weighing zone indicators displayed.

If the Overload audible alarm is enabled,

At 90% of maximum load = intermittent tone At 100% of maximum load = continuous tone

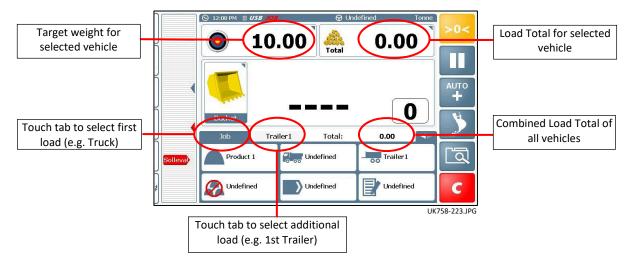
- 5. Press the key (or the Remote Enter Switch if fitted), to add to the load total.
- NOTE: Automatic Weight Entry is not possible.
 - 6. Press C to reset for the next loading job.



3.7 Split Loading (Trailers)

This function enables you to load multiple vehicles (e.g truck plus trailer(s) as a single job.

Touch the tab as shown below to select the vehicle being loaded.



Select the appropriate tab to load each vehicle in turn. The reference stores and target weight can be set independently for each vehicle. You may switch between vehicles as required.

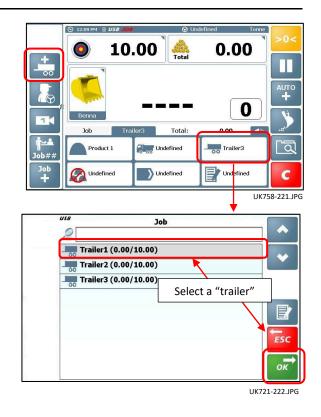
- NOTE: Once started, a job does not have to be completed and cleared before starting another job. This enables the operator to perform and log multiple loading tasks e.g. in a busy environment (ref. 2.8 'Jobs List').
- NOTE: Pressing the **C** key to complete and clear the job before starting a new job, resets the load totals to zero for all vehicles.

3.7.1 Add / select a vehicle ("trailer")

To create an additional vehicle (or "trailer") either,

(i) From the lefthand side menu, press and then
 'OK' to create a 'Trailer #' (or enter your own description if required).

 (ii) Select the "Trailer" reference store (this has to be enabled via the 'Home Screen Functions Setup' page in the calibration menu), and then the or key.



3.8 Blend ('Mix') Weighing Mode

You can choose to weigh dynamically or statically in this mode.



Select a "Mix", and enter a target weight for batch mixing. The instrument automatically calculates the target weight for each ingredient of the "recipe". Then simply weigh following the target weight ("Left to Load") display for each product in turn.

Products can be selected and weighed in any order.

1. Press on.

to switch Blend ("Mix") mode

2. Confirm the Mix selection from the list.

Example: "Mix 1" has the following ratio of ingredients;

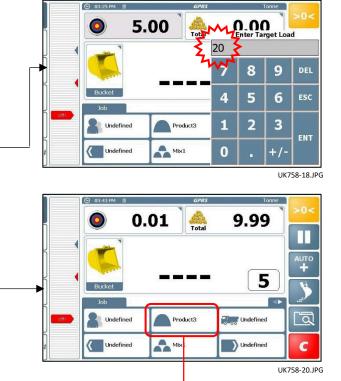
Product 1 = 2.00 parts Product 2 = 3.00 parts Product 3 = 5.00 parts

- 3. Enter the Target Weight.
- NOTE: The target weights for the individual products are <u>automatically</u> recalculated.

Example: For blending 20 tonnes of 'Mix 1' above, the individual Target weights will become;

Product 1 = 4.00t Product 2 = 6.00t Product 3 = 10.00t

4. Load the first product to match the target weight.



- 5. Select the next product (the target weight is <u>automatically</u> set).
- 6. Repeat loading for the remaining products.
- 7. Press C to reset for the next loading job.
- NOTE: "Blend ("Mix") Mode) is automatically disabled after pressing and the instrument returns to the normal (i.e. single product) weighing mode.

PRODUCTS

UK758-192.JPG

A 'Job Record' that includes the Load Data and Store references, is saved automatically to the database on the SD card, and printed out (if setup to do so).

A new Job Name is then created. Depending on the setting in the 'Setup', menu, the Store References will either default to those of the previous job, or to '**Undefined'**

The "Target Load" will revert to the last figure entered, and will need to be changed only if the next truck requires a different weight.

NOTE: Once started, a job does not have to be completed and cleared before starting another job. This enables the operator to perform and log multiple loading tasks e.g. in a busy environment (ref. 2.8 - 'Jobs List').

3.9 Reset for next Job

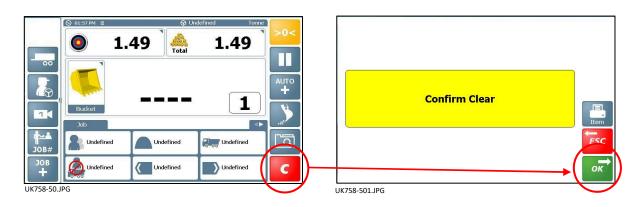
There are two options,

(i). Press C and then 📷 to reset for the next loading job. .

A print summary will be automatically generated if the instrument is setup to do so in the 'Setup' menu ('Printer and Serial Port Setup).

(ii).Alternatively, press 📇 to print a Job summary and clear the job total.

NOTE: When a Job Total cleared, the load data for that job is automatically save to the database on the SD card.



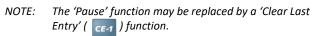
3.10 Pause / Resume Weighing Mode

If you wish to use the loader for non-weighing tasks, then simply **III** to de-activate the weighing mode.



'Pause' may be activated during a 'job', e.g. if you need to temporarily perform a non-weighing task.

Press **b** to resume weighing.



This setting is made via the 'Home Screen Functions Setup' page in the Calibration menu.



3.11 Reversing Camera Input

The LX-100 can also function as a video monitor for a reversing camera. The display will switch automatically from the 'Home' screen to camera view when reverse gear is selected.

Camera view can be also selected at any time by pressing the key. Press the key to return to the main operating screen.

NOTE: The Camera function is enabled from the 'Home Screen Setup' page in the 'Setup' menu.



4 'Nudge' - Adjusting Weight Calibration

	Sensor and Sampling Setup		
	Static Sample Time	•	
	Static Smoothing		
,	Static Auto Lock		
	Dynamic Bounce Filter		
9	Bounce Limit		
	Tip Off Pile Tip Off (Manual Add Off)		
ht 5	T Enable Nudge 🥥		ESC
	>0< Check Zero		
off 2	💵 Bounce Alarm 🔘	•	

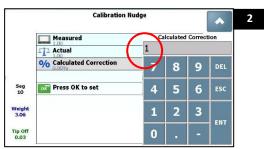
The Nudge function is switched on by default. From the Operator Setup menu (), select '**Calibration Nudge'**

If however, it has been switched off then it will not appear in the calibration menu. In this case, switch it on via the 'Sensor and Sampling Setup' menu (2.8).

Adjustment by Weight

Seg 10 Weight 3.06	Calibration Nudge	After performing the initial weight calibration, you may find that the load readings from the instrument are consistently different from weighbridge (weighscale) readings. This situation can also occur after maintenance or repair to the machine e.g. changing an attachment. Also, use the 'Nudge' function to adjust the weight calibration factors for individual attachments, where the initial factors were set using the 'COPYCAL' function.				
Tip Off 0.03	UK759-292.JPG	 The boom height ('Seg 1' to 'Seg 20') and the dynamic / live weights are displayed on the left side of the screen. 				
		Load a truck and note the weighbridge total against the instrument total for that load, e.g				
		Instrument reading ('Measured') 23.96 tonnes Scale reading ('Actual'): 24.78 tonnes				
		Enter the instrument reading (' Measured').				
		Enter the weighscale reading ('Actual')				

Adjustment by %



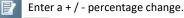
UK759-297.JPG

Alternatively, to manually adjust the cal factors by trial and error,

Set 'Measured' and 'Actual' to the same value i.e. '1'.

The % correction is displayed. Press or to accept.

Select '% Calculated Correction'.



Press

to accept.

5. Location Services

To enable location services requires a GPS signal and mobile Internet connection. 'Product', 'Destination' and 'Location' Store references must include latitude and longitude co-ordinates, and a 'Radius' setting.

5.1 Using Location Services

- 1. When the loader moves within the specified radius of the programmed co-ordinates of a Location or Destination Store Reference, the display will automatically switch to that reference.
- 2. However, to ensure that only the desired Product Reference is automatically selected, the display will not switch to the Product Store Reference associated with that location until reverse gear is selected i.e. you have chosen to dig in to the pile and reverse out with a bucket load.
- 3. If you wish to record the 'Destination' co-ordinates of the bucket load (e.g. a storage area), keep the boom lowered until you reach the tipping area. The bucket load should then be weighed in the normal way, during which the co-ordinates are logged.

to

5.2 Setting 'Destination' and 'Location' Co-ordinates

Both 'Destination' and 'Location' references may include GPS co-ordinates.

- Select or add (+) the Destination () or Location () reference.
- 2. Press to view the Reference settings.
- Undefined

 Image: Solution of the second s

State Zip Code DESTINATIONS

- 3. If you are at the correct position, then press enter the co-ordinates.
- NOTE:
- If you are not at the selected Destination or Location, but you know the GPS co-ordinates, then select the appropriate line and press manually.

Alternatively, the co-ordinates for that position are logged by performing the weighing routine.

UK721-52.JPG

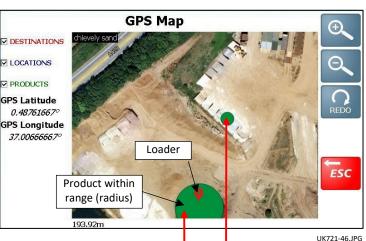
5.3 GPS Product Recognition

A moving map (Google Map) can be displayed via the 'Diagnostics' screen in the 'Setup' menu, which shows:-

- LOCATIONS () where the material originates e.g. a worksite, or location within a worksite.
- DESTINATIONS () where the material is sent e.g another location on the worksite, or to another worksite.
- PRODUCTS Locations of products on the worksite.

To display the map,

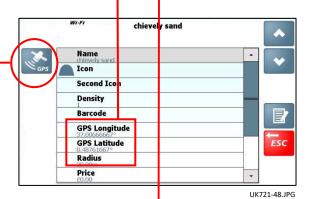
- 1. Press on the 'Diagnostics' screen.
- 2. Press _____ .



5.3.1 Set Product Co-ordinates and Radius

Using the examples shown, from the weighing screen,

- Select the product reference (e.g. 'Chievely Sand'), and then move close to the pile.
- 2. Press to enter the co-ordinates.
- 3. Select 'Radius' and enter the required value.
- NOTE: Where products are close to each other e.g. a row of storage bays, then do not set a large radius.



4. Repeat for each product.

In normal operation, the instrument displays the 'Home' screen. As you move within the product radius, the product reference is automatically set.



If products are in close proximity and incorrect selection occurs often, then reduce the 'radius ' setting for the adjacent products.
 W-FI
 10 mm shingle

 Name 10 mm shingle
 Image

 Icon
 Image

 Second Icon
 Image

 Barcode
 Image

 GPS Longitude
 Image

 37.000/23339
 Image

 GPS Latitude
 Image

 0.4870160P
 Image

 Price
 Image

UK721-47.JPG

6. Printing, Data Logging and Transfer

6.1 Data Transfer Options

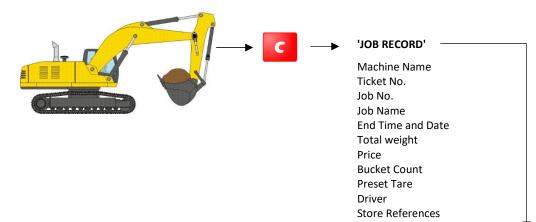
NOTE: Some options may not apply, depending on the setup of your system.

ТҮРЕ	MODE	OPTION	
PRINTER	RS232 SERIAL (Normally COM 2)	[OFF]	No automatic printout after a load is cleared, but Job Records can be printed manually
		AUTOMATIC MODE	A Job Record ('Ticket') in one of 3 formats, is printed automatically after a load is cleared.
		'LOAD BY LOAD'	Ticket includes space for Name, Address and Signature of customer.
		'SHORT LOAD BY LOAD'	As above but excludes space for Name, Address and Signature of customer.
		'LIFT BY LIFT'	As above but also lists individual bucket weights.
		EXTENDED INFORMATION	Ticket includes extra text entered for 'Description 1' to 'Description 4' in the Product Stores.
		PRINTER TYPE	['ICP300 (1)'] / '['ICP300 (2)' / EPSON TM295' / 'BIXOLON'
			'ICP300 (1)' has a slow print mode so that it can print tickets with large icons, without handshaking.
			'ICP300 (2)' has a fast print mode for general printing with small or no icons.
			The RDS ICP300 printer supports bitmap characters, however most third-party printers do not. If you are using a printer other than the RDS printer. LX-100 will then <u>not</u> output bitmap characters. Selecting ' BIXOLON ' enables 48 characters per line, and a paper "cutter" command
		No. OF DUPLICATES	Sets the no. of copies of a ticket that will be printed.
DATA	USB (PEN)	EXPORT LIST VIA USB	Reference Stores, Jobs List, Job Records
		IMPORT AND OVERWRITE LIST VIA USB	Reference Stores, Jobs List
		IMPORT AND ADD LIST VIA USB	Reference Stores, Jobs List
	USB (MOBILE PHONE)	EXPORT LIST VIA ANDROID DEVICE	Reference Stores, Jobs List, Job Records
	ETHERNET / 3G MODEM (EMAIL)	EXPORT LIST TO EMAIL	Reference Stores, Jobs List, Job Records
	ETHERNET / 3G MODEM (WEBSERVER)	EXPORT LIST TO WEBSERVER	Reference Stores, Jobs List, Job Records
		IMPORT LIST FROM WEBSERVER	Reference Stores, Jobs List
	RS232 SERIAL (Normally COM 1)	.CSV - LOAD BY LOAD LM8K	Data output in .CSV format if compatibility with existing Loadmaster 8000 data is required.
	e.g. RADIO MODEM	.CSV - LIFT BY LIFT LM8K	As above, but also lists individual bucket weights. (.CSV line sent to Com Port when load is cleared.)
	DATALOGGER PC CABLE	.XML	"SQL Queries" from networks or PC running software (i.e. "Isosync"). Data returned from SQL query in .XML format.
	etc	.CSV - LOAD BY LOAD	CSV data output closely matching XML data output in mode, but in CSV format
		.CSV - LIFT BY LIFT	As above, but also lists individual bucket weights
	ETHERNET TCP/IP i.e. With Ethernet radio modem or direct cable	SQL	"SQL Queries" from networks or PC running software (i.e. "Isosync"). Data returned from SQL query in .XML format.

6.2 Reference Stores and Job Records

An incremental Job No. is created automatically for each new loading task. When the **C** button is pressed, A 'Job Record' that includes the Load Data and the Store references, is saved automatically to the database on the SD card, and printed out (if setup to do so).

NOTE: Each of the stores can have an unlimited no. of references. The programmable content of each Reference Store is shown in the table below.



	DATABASE on	SD Card - Refer	ence Stores (exe	cluding the 'Mix	(' store)		
Programmable Content	Product	Customer	Destination	Location	Truck	Haulier	Note
Name / Text	0	0	0	0	0	0	0
Weight					0		
Target					0		
lcon 1	0						
lcon 2 [2]	0						
Density	0						
Barcode	0		0	0	0		0
GPS Long.	0		0	0			
GPS Lat.	0		0	0			
Radius	0		0	0			
Price	0						
Description 1	0		0	0			0
Description 2	0		0	0			0
Description 3	0		0	0			0
Description 4	0		0	0			0
Phone No.		0				0	
Email		0				0	
Street		0	0	0		0	
City		0	0	0		0	
State		0	0	0		0	
Zip Code		0	0	0		0	
'LM8K Index' [3]	0	0					

- [1] The choice of Reference stores available on the Home Screen depends on which are enabled via the 'Home Screen Functions Setup' menu.
- [2] Currently only a requirement for COPRO regulations (Belgium), for 'BENOR' and 'CE1137' to appear on printouts.
- [3] 'LM8K Index' Only required if you are operating Loadmaster Alpha 100 and Loadmaster 8000 series instruments on the same site, and want compatibility with the .CSV data format exported from the Loadmaster 8000/8000i. The 'LM8K Index' entries would correspond to the Customer Nos. / Product Nos. stored in the Loadmaster 8000/8000i.

O Undefin

2.00

1

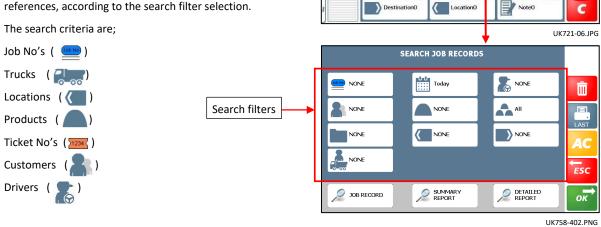
П

a

6.3 Job Records

The database can be searched using search filters to create the following reports,

- 'Job Report' a list of individual Job Records with load data, according to the search filter selection.
- 'Summary Report' a list of weight totals and no. of loads for individual store references, according to the search filter selection.
- 'Detailed Report' a list of weight totals and no. of loads for each different combination of store references, according to the search filter selection.



S 02:07 PM

Product 0

8.00

Customer O

6.3.1 Search Job Records

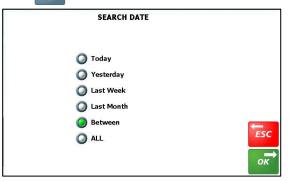
Select

Search records within a specified time-period

Select the search criteria:-

For the date you have the following options (default = 'Today'). If you select 'Between', a calendar is displayed to select the 'From' date. Press 'OK' to select the 'To' date.

if you wish to search for job records created within a more specific time period.



		1	DATE FRO	M		
•		Jan	uary 2	006		
S	М	Т	W	Т	F	S
25	26	27	28	29	30	31
1	2	3	4	5	6	7
8	9	10	11	12	13	14
15	16	17	18	19	20	21
22	23	24	25	26	27	28
29	30	31	1	2	3	4

UK721-80.JPG

Search by Store Reference

For all other criteria, you have 3 options to choose from.

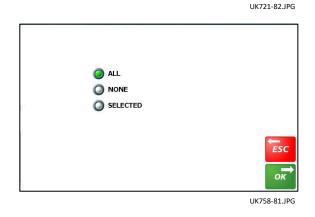
E.g. for 'Customers',

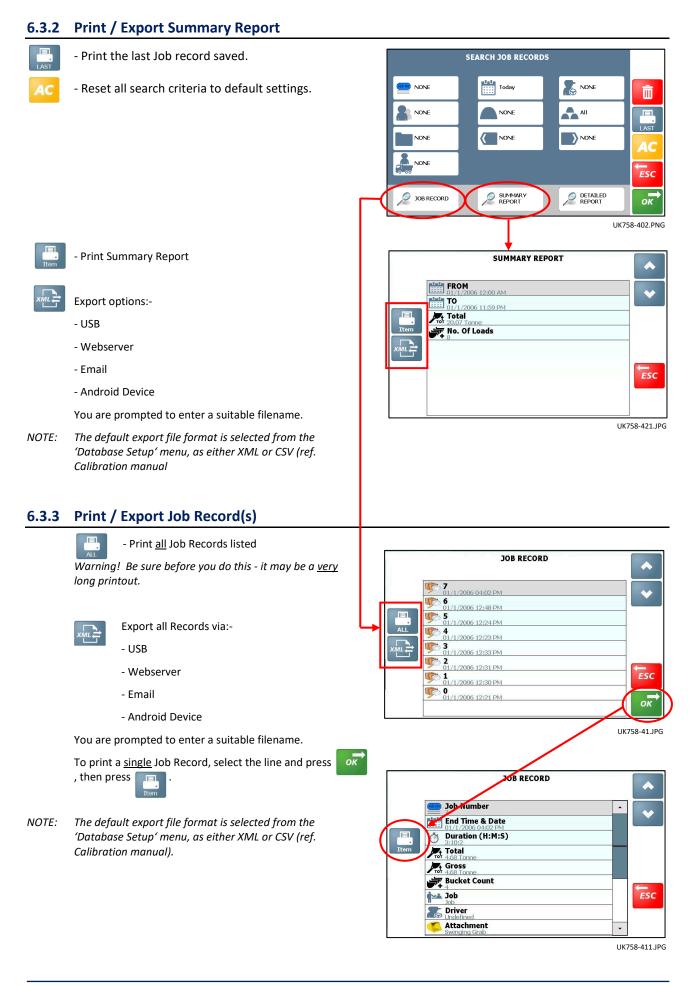
'ALL' - Include all 'Customers' in the search.

'NONE' - Exclude 'Customers' from the search.

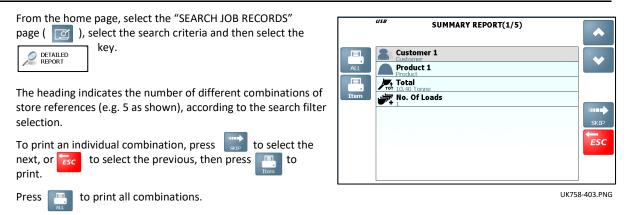
'**SELECTED**' - Include only selected 'Customers' from the list displayed, for the search.

(Default = 'NONE')





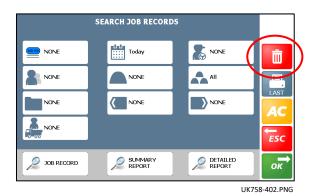
6.3.4 Print Detailed Report(s)



6.3.5 Delete Job Record(s)



2. Enter the Technician menu PIN (factory default = 1234).



- 3. Select the jobs to delete by "Date from" / "Date to".
- to select time. 4. If you need a more precise search, press
- or and then once again to delete the selected jobs. 5. Press
- NOTE: Deleting all Job records is also possible from the calibration menu:-

"Technician"

- "Database Setup"
- ► "Job Records "Press edit button to reset all job records"

		I	DATE FRO	м		
(Jan	uary 2	015		►
S	М	Т	W	Т	F	S
28	29	30	31	1	2	3
4	5	6	7	8	9	10
11	12	13	14	15	16	17
18	19	20	21	22	23	24
25	26	27	28	29	30	31
1	2	3	4	5	6	7

UK721-100.JPG

Totals 6.4

6.4.1 **Grand Total**

. .

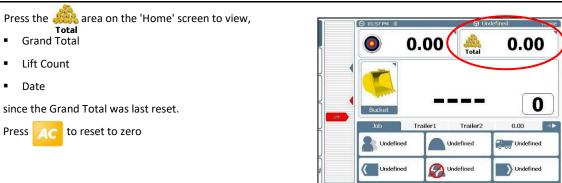
Press the *‱*

Lift Count

AC

Date

Press

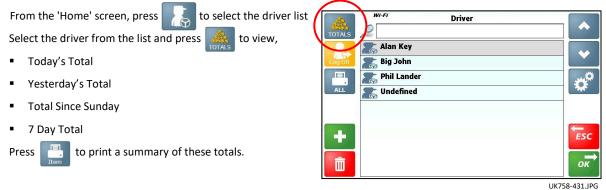


C UK758-22.JPG

a

6.4.2 Driver Totals

You can view (and print if enabled) a summary of the loads saved over the previous week.



6.4.3 Reference Store Totals

You can view (and print if enabled) a summary of the loads saved over the previous week.

to

NOTE: Applies to all Reference Stores

Select the appropriate Reference Store.

Select the reference from the list and press view,

- Today's Total
- Yesterday's Total
- Total Since Sunday
- 7 Day Total

Press E to print a summary of these totals.

🗩 01:57 PM 🔳		⊕ Ur	defined T	onne
0	0.00	Total	0.00	
				A
- Change	_			
Bucket			U	
Bucket Job	Trailer1	Trailer2		
		Trailer2 Undefined		

7. Operating Parameters

The LX-100 system is designed to operate within the following parameters:

Environmental:

Climatic environment:	Indicator, printer: Closed, non-condensing, -25/+50 $^\circ\mathrm{C}$		
Transducers, sensors:	Open, condensing, -25/+50°C		
Sealing: Head unit:: Sensors: Junction Box:	IP34 (mount in an enclosed cab) IP67 IP65		
Pressure range:	0-250bar / 0 - 400 bar.		
Electrical:			
Supply voltage: Current: EMC Emission/Immunity	11 – 30V dc 1000 mA max. EN ISO 13766 : 2018		
	EN ISO 14982 : 2009		
EM classification:	E3		
EM classification:	E3		

Issue 1.0:	13.5.14	Original Issue
Issue 1.1:	27.5.14	Ref. CRQ 5655
Issue 2.0:	30.6.14	Revisions for S/W Ref. IS200002rev.00 / LX200002rev.00
Issue 2.1:	30.6.14	Page 7: Updated rear view picture. Section 6.1 (p.34): Edited table - data output options as per calibration manual
Issue 2.2	20.8.14	Revised section 2.8.4
Issue 2.3	15.10.14	Ref CRQ 5995
Issue 3.0	4.3.15	Ref CRQ 6289
Issue 4.0	24.10.17	Ref CRQ 8049
Issue 5.0	03.05.2022	Ref. TTL_DRF_SDC500-10-758_UK_Rev 5-0
Issue 5.2	30.10.2023	Ref TTL_DRF_SDC500-10-758_UK-FR-GM_Rev 5-2

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Software Revisions	:
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Database:	DBIS100001 rev03
Weighing Module:	LX200004 rev02

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Please visit our website for technical support or other product information. Replacement user manuals are available on request.

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